

Obj

• Big Picture

• 2nd order circuits

• Initial Conditions



$\int$ or $\frac{d}{dt}$

$$i_c = C v_c'$$

$$v_L = L i_L'$$

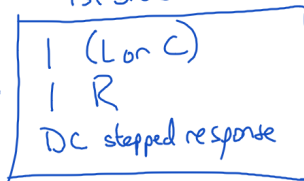
$$v_c = \frac{1}{C} \int_{t_0}^+ i_c(t) dt + v_c(t_0)$$

$$i_L = \frac{1}{L} \int_{t_0}^+ v_L(t) dt + i_L(t_0)$$

Test 1 (3 weeks)

Big Picture

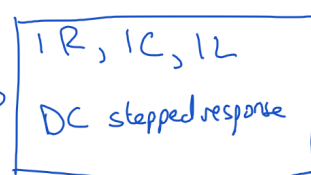
1st order



$$v_c(t) = V_{\infty} + (V_0 - V_{\infty}) e^{-t/\tau}$$

$$i_L(t) = I_{\infty} + (I_0 - I_{\infty}) e^{-t/\tau}$$

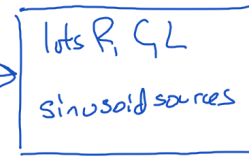
2nd order



Initial Conditions
Source-free ckt's
step response

Test 2 (3 weeks)

any order



phasors!

Test 3 (3 weeks)

Second Order Circuits

• Find Initial Conditions

First order no matter what asked to find, $v_c: t < 0 \Rightarrow v_c(0^+) + v_c(\infty)$
 $i_L: t < 0 \Rightarrow i_L(0^+) + i_L(\infty)$

Second order find what you are asked to find

eg. $v_R(t)$

$$v_R(0^+)$$

$$v_R'(0^+)$$

$$v_R(\infty)$$

• Plug n Chug

First order

$$A + Be^{-kt}$$

$$V_{\infty} + (V_0 - V_{\infty})e^{-t/\tau}$$

$$\bullet Ae^{-\underline{k}_1 t} + Be^{-\underline{k}_2 t}$$

$$\bullet A\underline{t}e^{-\underline{k} t} + Be^{-\underline{k} t}$$

$$\bullet [\underline{A} \cos(\underline{\omega} t) + \underline{B} \sin(\underline{\omega} t)] e^{-\underline{k} t}$$

Second Order

Initial Conditions

1st Order Circuits

$t=0^+$

$$\begin{matrix} v_C(0^+) \\ i_L(0^+) \end{matrix}$$

no matter what we were asked to find!

★ $t=\infty$

$$\begin{matrix} v_C(\infty) \\ i_L(\infty) \end{matrix}$$

2nd Order Circuits

$t=0^+$

$$\begin{matrix} x(0^+) \\ x'(0^+) \end{matrix}$$

eg

$$\begin{matrix} v_R(0^+) \\ v_R'(0^+) \end{matrix}$$

★ $t=\infty$

$$\begin{matrix} x(\infty) \end{matrix}$$

$$\begin{matrix} v_R(\infty) \end{matrix}$$

Method 2nd Order I.C.

① Goal: I_{L0}, I_{C0}

• Draw $t < 0$, DCSS

• $\frac{1}{s} \Rightarrow \frac{1}{s} I_{L0}$ } $\Rightarrow \downarrow I_{L0}$

• Find I_{L0}, I_{C0}

② Goal: $x(0^+)$ ex. $v_R(0^+)$

• Draw $t=0^+$

• $\frac{1}{s} \Rightarrow \downarrow I_{L0}$ } $\Rightarrow \downarrow I_{L0}$

• Find the requested $x(0^+)$ ex $v_R(0^+)$

③ Goal: $x'(0^+)$ ex $v_R'(0^+)$

• Use $t=0^+$ diagram

$$\begin{matrix} v_L = L i_L' \Rightarrow i_L' = \frac{1}{L} v_L \\ i_C = C v_C' \Rightarrow v_C' = \frac{1}{C} i_C \end{matrix}$$

definitely use

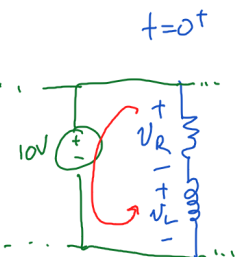
$$\begin{matrix} v' = i'R \\ i_1' + i_2' = 0 \\ v_1' + v_2' = 0 \end{matrix}$$

Ω Law

KCL

KVL

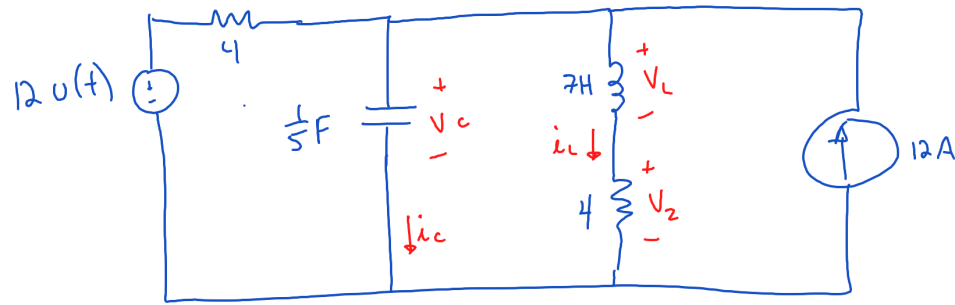
may or may not use



$$\begin{aligned} 1) v_L(0^+) \\ 2) i_L'(0^+) = \frac{1}{L} v_L(0^+) \\ 3) i_R' = i_L' \\ v_R' = R i_R' \end{aligned}$$

$$\begin{aligned} v_L'(0^+) \\ +10 - v_L - v_R = 0 \\ -v_L' - v_R' = 0 \\ v_L'(0^+) = -v_R'(0^+) \end{aligned}$$

Ex



Find

$$v_c(0^+) = 24V$$

$$i_L(0^+) = 6A$$

$$v_2(0^+) = 24V$$

$$v_L(0^+) = 0V$$

$$v_c'(0^+) = 15V/s$$

$$i_L'(0^+) = 0A/s$$

$$v_2'(0^+) = 0V/s$$

$$v_L'(0^+) = 15V/s$$

③ Using the $t=0^+$ diagram, find $x'(0^+)$

$$\begin{cases} i_c = C v_c' \\ v_L = L i_L' \end{cases}$$

always

maybe

$$\begin{cases} v_R' = i_R' \cdot R \\ v_1' + v_2' = 0 \\ i_1' + i_2' = 0 \end{cases}$$

Ω 's Law

KVL

KCL

$$\begin{aligned} v_c' &= \frac{1}{C} i_c \\ &= \frac{1}{5} (3) \\ &= 15V/s \end{aligned}$$

$$\begin{aligned} \text{KCL: } 3 + i_c + 6 - 12 &= 0 \\ \Rightarrow i_c &= 3 \end{aligned}$$

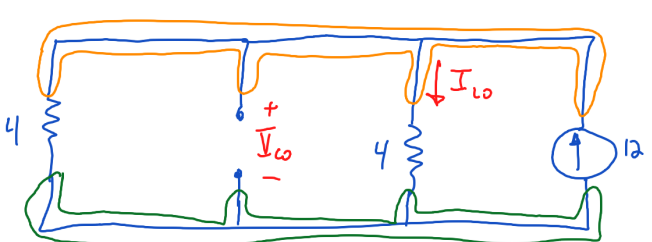
$$i_L' = \frac{1}{L} v_L = \frac{1}{7} (0) = 0A/s$$

$$\begin{aligned} v_2' : +v_L' + v_2' - v_c' &= 0 \\ v_2' &= v_c' - v_L' = 15 - 0 \end{aligned}$$

$$v_2' = 4 i_L' = 4(0) = 0V/s$$

$$\begin{aligned} v_L' : v_L' + v_2' - v_c' &= 0 \\ v_L' &= v_c' - v_2' \\ &= 15 - 0 \\ &= 15V/s \end{aligned}$$

① Draw $t < 0$ I_{L0} , V_{c0} always

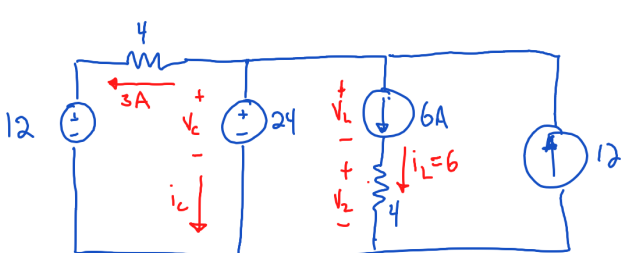


$$I_1 = I_s \frac{R_2}{R_1 + R_2}$$

$$I_{L0} = 12 \frac{4}{4+4} = 6A$$

$$V_{c0} = (4\Omega)(6A) = 24V$$

② Draw $t=0^+$ $x(0^+)$



$$v_2 = (4)(6) = 24$$

$$v_L : -24 + v_L + 24 = 0$$

$$v_L = 0V$$